



**Niehues**

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*Danfoss*

Technical Information

# Speed and Temperature Sensor

## Hydrostatic Propel Products



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**Revision history**
*Table of revisions*

Date	Changed	Rev
January 2021	Changed document number from 'BC00000047' to 'BC152886482203' and added new speed sensor	0701
January 2020	Added MP1P and MP1M target ring information	0508
November 2019	Corrected speed sensor pinout information.	0507
June 2019	Formula for temperature calculation corrected.	0506
May 2019	Minor update.	0505
February 2018	Minor update.	0504
November 2017	Minor layout changes.	0503
December 2015	Data for size 210 of H1B motor.	0502
2011-2014	Various changes.	BA-FB
Sep 2009	First edition	AA

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## General Information

### Description

Function of the speed sensor is to detect the shaft speed. Typically the sensor is mounted to the housing of a Danfoss pump or motor and senses the speed from a target ring that is rotating inside the pump or motor.

Because of the digital output signals for speed the sensor is ideal for high and low speed measurements.

The speed sensor is designed for rugged outdoor, mobile or heavy industrial speed sensing applications.

The detection of the speed is contactless. It is custom-designed for Danfoss. It is a *Plug and Perform* device that does not need any calibration or adjustments.

For diagnostics and other purposes, some sensor also has the capability to detect the driving direction and the case oil temperature.

### Theory of Operation

The speed sensor is externally powered and, in response to the speed of the target ring, outputs a digital pulse signal. A magnet inside the sensor provides the magnetic field that changes with the position of the target teeth.

The target ring is attached to the cylinder block or the shaft. Hall sensors change from high/low state as the target teeth pass by the sensor's face. The digital (on-off-on-off) pulse train is fed to a controller, which interprets its rate of change as a speed.

Some speed sensor uses two Hall sensors with specific distance and orientation resulting in a pulse train output shift of 90° between the two sensors. A logic circuit decodes the two signals to provide an additional direction indication (high or low depending on direction).

Due to the design of the sensor, the duty cycle (ratio between on and off time at constant speed) of both speed signals at any working condition is close to 50 % and can be used for better resolution at low speeds.

### Speed Rings

Speed rings vary according to the diameter of the cylinder block or shaft on which they are installed. The number of teeth can be seen in the technical information of the H1 pumps and H1 bent axis motors.

They may be ordered directly from the pump manufacturer or retrofitted to existing pumps and motors by authorized service centers (specialized tooling is required for mounting).

### Target Ring

Speed (target) rings vary according to the diameter of the cylinder block or shaft on which they are installed. The number of teeth is shown in the table below.

*The number of speed (target) ring teeth*

H1P size	045/053	060/068	069/078	089/100	115/130	147/165	210/250
Teeth	79	86	86	92	102	108	90

*The number of speed (target) ring teeth*

H1B size	060	080	110	160	210	250
Teeth	71	78	86	95	104	108

*The number of speed (target) ring teeth*

MP1P size	028/032	038/045
Teeth	9	11

## Technical Information

### Speed and Temperature Sensor for Hydrostatic Propel Products

#### General Information

The number of speed (target) ring teeth

<b>MP1M size</b>	<b>020/024</b>
Teeth	9

Target ring for integrated drives

<b>Integrated drive size</b>	<b>IDMV 044</b>	<b>IDMV 053</b>
<b>Number of teeth</b>	75	79

If a product is not seen in the tables, refer to technical information of the specific product.

#### Temperature Range

Parameter	Minimum	Maximum
Operation temperature range	-40 °C	104 °C

115°C Intermittent = Short term; t < 1min per incident and not exceeding 2 % of duty cycle based load-life.

#### Protection Characteristics

Parameter	Data
Protection Code (IP class) according IEC 60529 and DIN 40050	IP 67 (without connector installed) IP 69k (with connector installed)
EMC Emission	EN 61000-6-3
EMC Immunity (EMI)	100 V/m incl. 1 kHz AM 80 %; ISO 11452-5 and -2
ESD	EN 61000-4-2 Air discharge: 15 kV Contact discharge: 8 kV
Vibration	30 G (294 m/s <sup>2</sup> )
Shock	50 G (490 m/s <sup>2</sup> )
Case maximum pressure	5 bar [72.5 psi]

#### Mating Connectors

There are available two types of mating connectors Assembly Bag DEUTSCH DTM06-6S, Black and Grey.

Ordering number	
<b>11033865</b>	<b>11033863</b>
Assembly Bag, DEUTSCH DTM06-6S-E004; black, (24-20 AWG) 0.21 -0.52 mm <sup>2</sup>	Assembly Bag, DEUTSCH DTM06-6S, gray, (24-20 AWG) 0.21 -0.52 mm <sup>2</sup>

#### Available Sensors

There are two speed sensors available according to different supply voltage range: 4.5 to 8 V<sub>DC</sub> and 7 to 32 V<sub>DC</sub>.

Description	Order number	
	<b>149055</b>	<b>11232698</b>
Supply voltage	4.5 – 8 V	7 – 32 V
Speed signals	Two, 90° Phase shift	Two, 90° Phase shift

## Technical Information

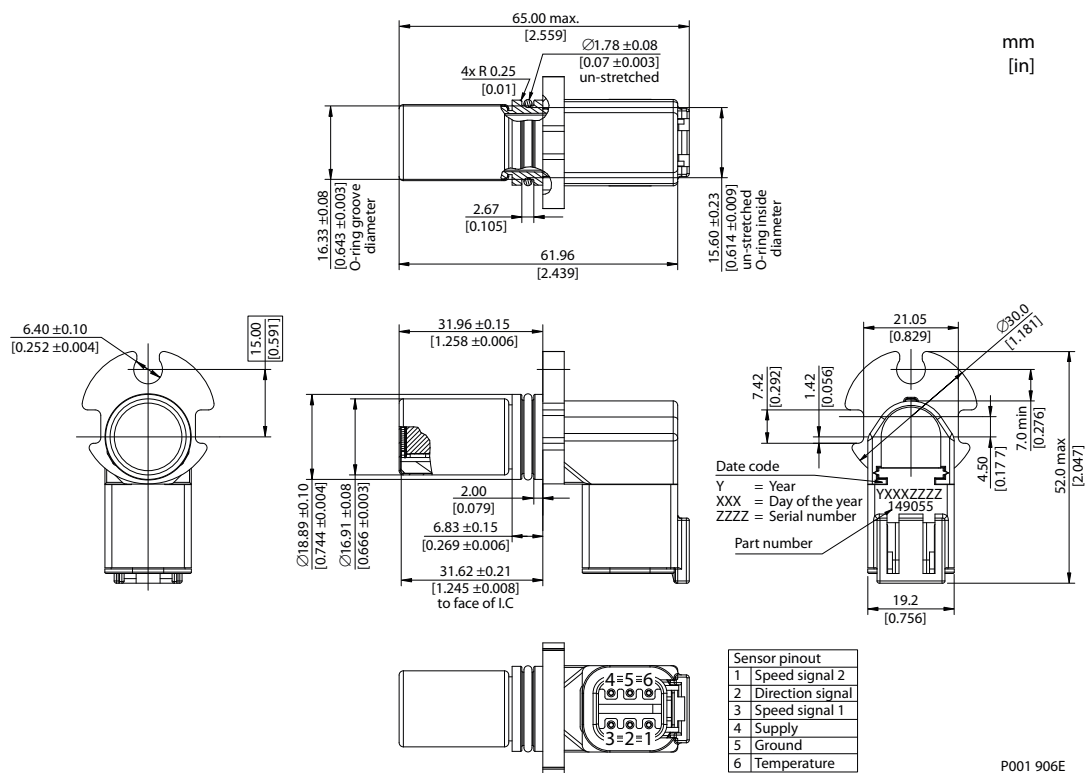
### Speed and Temperature Sensor for Hydrostatic Propel Products

#### General Information

Description	Order number	
	149055	11232698
Direction signal	One	One
Temperature signal	One	One

For more information, see and .

#### Dimensions



For more details about Mating connector, see the chapters *Speed Sensor 4.5 – 8 V Technical Data* and *Speed Sensor 7 – 32 V (1 Speed Signal)*

#### Sensor Installation

The sensor is positioned in the housing and fastened by one screw.

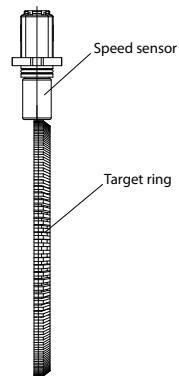
The gap between the sensor and the target does not need to be adjusted, nor it does need to be rotated for direction sensing.



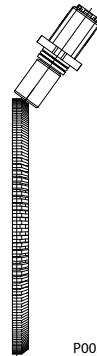
### General Information

Example:

**H1B** Motor housing  
SAE & DIN



**H1B** Motor housing  
Cartridge

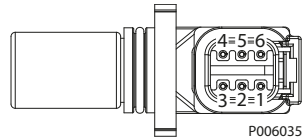


P003 523E

## Technical Information

**Speed and Temperature Sensor for Hydrostatic Propel Products**
**Speed Sensor 4.5 – 8 V Technical Data**

Speed sensor connector, 6-pin



P006035

1. Speed signal 2
2. Direction signal
3. Speed signal 1
4. Supply
5. Ground
6. Temperature

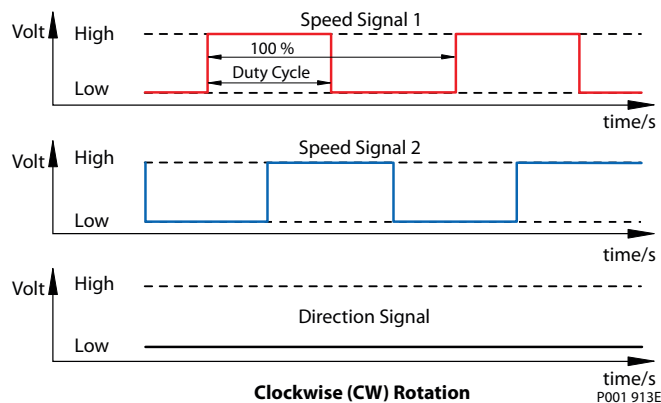
## Technical data

Parameter	Min.	Nom.	Max.	Note
Supply voltage	4.5 V <sub>DC</sub>	5 V <sub>DC</sub>	8 V <sub>DC</sub>	Regulated supply voltage. Reverse polarity protected.
Supply protection	–	–	30 V <sub>DC</sub>	Shuts off above 9 V.
Max. required supply current	–	–	25 mA	At supply voltage
Max. output current	–	–	50 mA	
Operation mode	NPN & PNP			Push-Pull amplifier
Temperature signal	–40°C = 2.318V	–	100°C = 0.675V	
Output low	5 %	8.5 %	12 %	Ratiometric output voltage Low state > 0 V to provide wire fault detection
Output high	88 %	91.5 %	95 %	
Detectable frequency range	1 Hz	–	10 000 Hz	
Ordering number	<b>149055</b>			
Color of connector	Black			

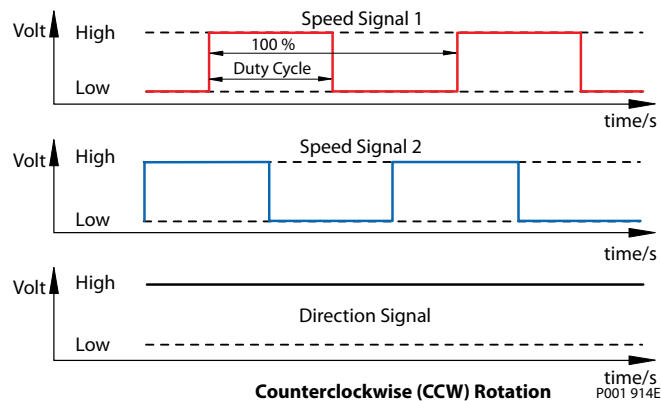
**Duty Cycles**

Output speed signal technical data and duty cycles graphs (clockwise and counterclockwise rotation).

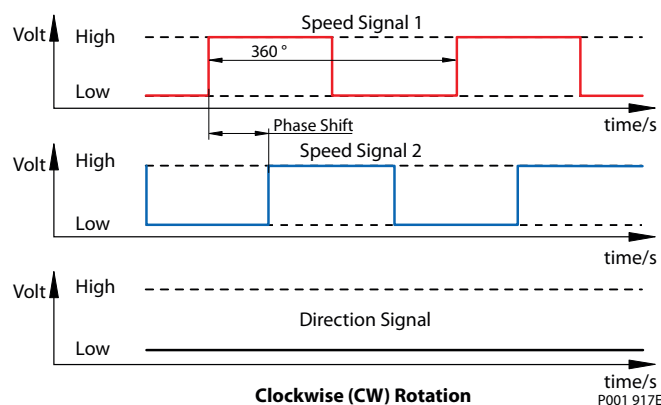
Duty cycle clockwise rotation





**Speed Sensor 4.5 – 8 V Technical Data**
*Duty cycle counterclockwise rotation*

*Output speed signal technical data*

Parameter		Min.	Nom.	Max.
Output speed signal 1 Square wave	Low	5 %	8.5 %	12 %
	High	88 %	91.5 %	95 %
Output speed signal 2 Square wave	Low	5 %	8.5 %	12 %
	High	88 %	91.5 %	95 %
Duty cycle	Clockwise (CW)	42.5 %	50 %	57.5 %
	CounterClockWise (CCW)	42.5 %	50 %	57.5 %
Phase shift		70°	97.5°	125°
Square wave Direction signal	Low = CW	5 %	8.5 %	12 %
	High = CCW	88 %	91.5 %	95 %

*Phase shift clockwise rotation*


Low state > 0 V to provide wire fault detection.

Ratiometric output voltage means that the output signal is proportional to the supply voltage. *Example:*

5 % of 5000 mV sensor supply = 250 mV sensor signal accepted as low output voltage

5 % of 4900 mV sensor supply = 245 mV sensor signal accepted as low output voltage

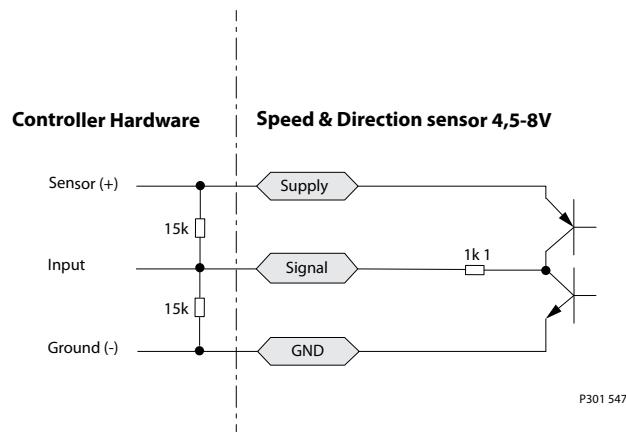
For more information see [Wire Fault Detection](#) on page 14 and [Output Signals](#) on page 10.

## Speed Sensor 4.5 – 8 V Technical Data

### Wire Fault Detection

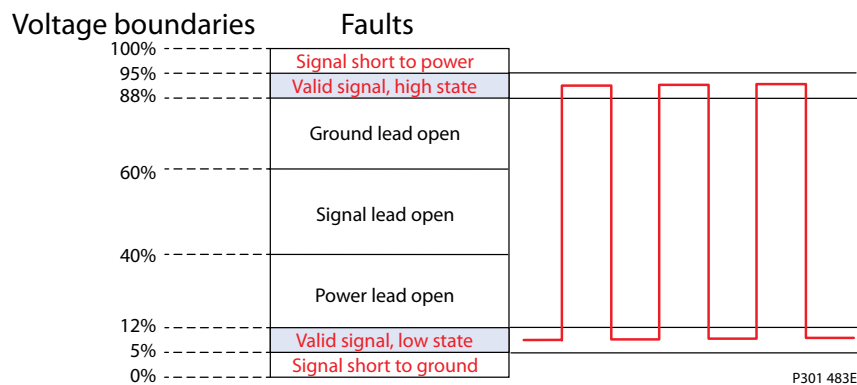
The output voltage levels are defined for a direct connection of the sensor to supply. The outputs are directly connected to a load which is 15k Ohm to ground and 15k Ohm to Supply.

The signal outputs are protected by an 1100 ohm (1k1) resistor. Speed signal 1 (pin 3) offers an advanced error detection by providing different signal levels in case of an error.

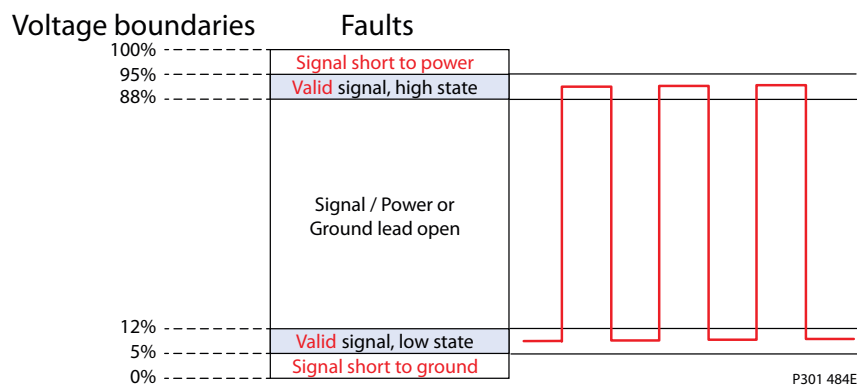


### Output Signals

Speed signal 1 (pin 3) signal conditions:



Speed signal 2 (pin 1) and direction signal (pin 2) signal conditions:



**Speed Sensor 4.5 – 8 V Technical Data**
**Temperature Sensor Data**

For calculation of the case fluid temperature and the output signal voltage, see the formulas below:

**$V_O$  – Measured output voltage (V)**

$$V_O = (-3.88 \cdot 10^{-6} \cdot T^2) + (-1.15 \cdot 10^{-2} \cdot T) + 1.8639$$

**T – Temperature (°C)**

$$T = -1481.96 + \sqrt{2.1962 \cdot 10^6 + \frac{(1.8639 - V_O)}{3.88 \cdot 10^{-6}}}$$

Output signal voltage vs. Temperature

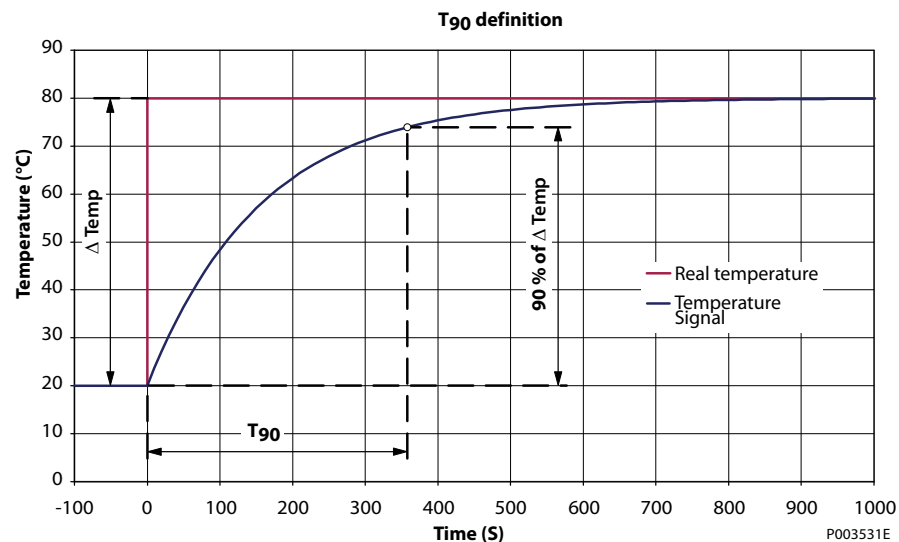
Temperature range							
-55 °C**	-40 °C	-30 °C	0 °C	+30 °C*	+80 °C	+100 °C	+130 °C**
2.485 V	2.318 V	2.205 V	1.864 V	1.515 V	0.919 V	0.675 V	0.303 V

\* Accuracy:  $\pm 1.5$  to  $\pm 4$  °C

\*\* Accuracy:  $\pm 2.5$  to  $\pm 5$  °C

**Response time in fluid**

$T_{90}$  definition



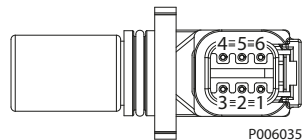
Response time in fluid ( $T_{90}$ ) = 360 s

## Technical Information

**Speed and Temperature Sensor for Hydrostatic Propel Products**
**Speed Sensor 7 - 32 V**

 Speed Sensor 7 – 32 V<sub>DC</sub> technical data and information about connector.

Speed sensor connector, 6-pin



Pinout:

1. Speed signal 2
2. Direction signal
3. Speed signal 1
4. Supply
5. Ground
6. Temperature signal

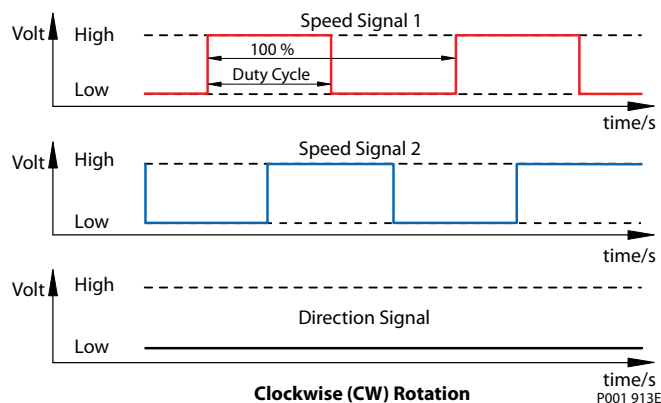
## Technical data

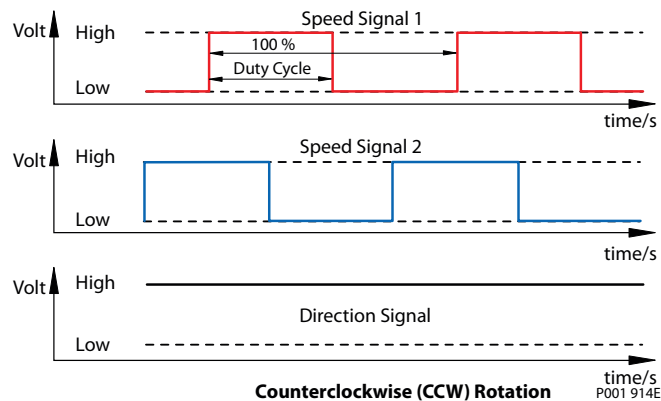
Parameter	Min.	Max.	Note
Supply voltage range	7 V <sub>DC</sub>	32 V <sub>DC</sub>	
Supply protection	–	36 V <sub>DC</sub>	36 V <sub>DC</sub> over voltage protection -36 V <sub>DC</sub> permanent reverse polarity protection
Max. required supply current	–	30 mA	
Max. output current	–	50 mA	
Operation mode	<b>NPN open collector</b>		Internal 2k7 pull-up resistor to supply
Output low signal range	2 %	10 %	Max. output voltage 24 V <sub>DC</sub>
Output high signal range	55 %	85 %	
Detectable frequency range	1 Hz	10 000 Hz	
Speed sensor order number	11232698		
Color of connector	Yellow		

**Duty Cycles**

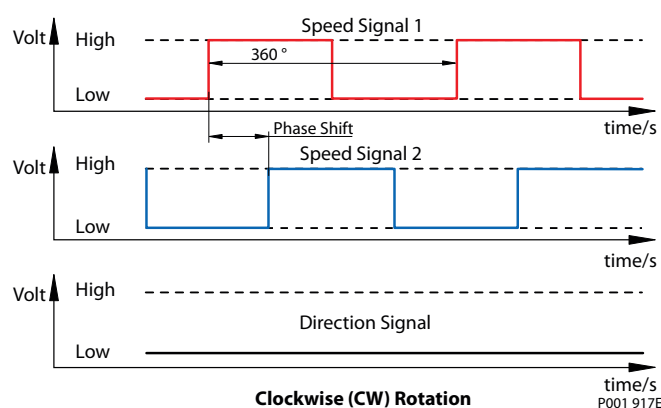
Output speed signal technical data and duty cycles graphs (clockwise and counterclockwise rotation).

Duty cycle clockwise rotation



**Speed Sensor 7 - 32 V**
*Duty cycle counterclockwise rotation*

*Output speed signal technical data*

Parameter		Min.	Nom.	Max.
Output speed signal 1 Square wave	Low	5 %	8.5 %	12 %
	High	88 %	91.5 %	95 %
Output speed signal 2 Square wave	Low	5 %	8.5 %	12 %
	High	88 %	91.5 %	95 %
Duty cycle	Clockwise (CW)	42.5 %	50 %	57.5 %
	CounterClockWise (CCW)	42.5 %	50 %	57.5 %
Phase shift		70°	97.5°	125°
Square wave Direction signal	Low = CW	5 %	8.5 %	12 %
	High = CCW	88 %	91.5 %	95 %

*Phase shift clockwise rotation*


Low state > 0 V to provide wire fault detection.

Ratiometric output voltage means that the output signal is proportional to the supply voltage. *Example:*

5 % of 5000 mV sensor supply = 250 mV sensor signal accepted as low output voltage

5 % of 4900 mV sensor supply = 245 mV sensor signal accepted as low output voltage

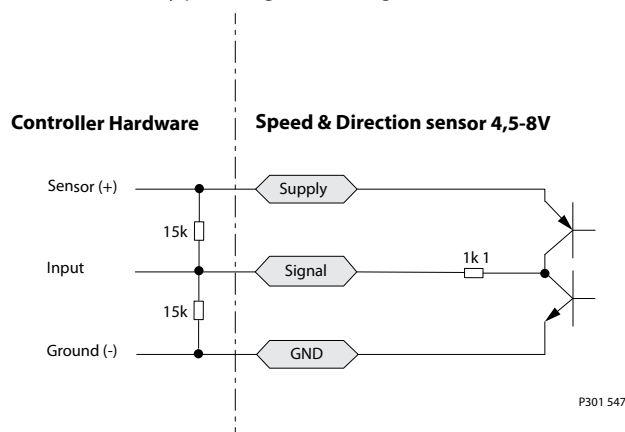
For more information see [Wire Fault Detection](#) on page 14 and [Output Signals](#) on page 10.

## Speed Sensor 7 - 32 V

### Wire Fault Detection

The output voltage levels are defined for a direct connection of the sensor to supply. The outputs are directly connected to a load which is 15k Ohm to ground and 15k Ohm to Supply.

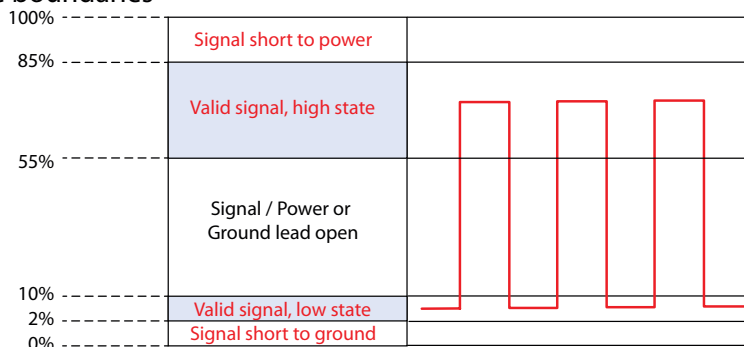
The signal outputs are protected by an 1100 ohm (1k1) resistor. Speed signal 1 (pin 3) offers an advanced error detection by providing different signal levels in case of an error.



### Output Signals

Speed signals 1, 2 and direction signal

#### Voltage boundaries



### Temperature Signal

For calculation of the case fluid temperature and the output signal voltage, see the formulas below.

#### $V_o$ – Measured output voltage (V)

$$V_o = (-3.88 \cdot 10^{-6} \cdot T^2) + (-1.15 \cdot 10^{-2} \cdot T) + 1.8639$$

#### T – Temperature (°C)

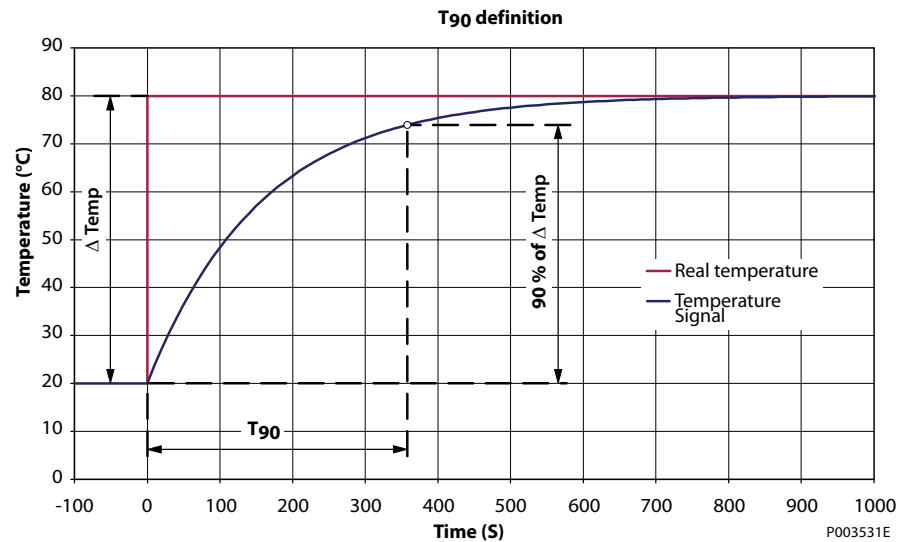
$$T = -1481.96 + \sqrt{2.1962 \cdot 10^6 + \frac{(1.8639 - V_o)}{3.88 \cdot 10^{-6}}}$$

**Speed Sensor 7 - 32 V**
*Output signal voltage vs. Temperature*

Temperature range							
-55 °C**	-40 °C	-30 °C	0 °C	+30 °C*	+80 °C	+100 °C	+130 °C**
2.485 V	2.318 V	2.205 V	1.864 V	1.515 V	0.919 V	0.675 V	0.303 V

 \* Accuracy:  $30 \pm 2.5$  °C (max)

 \*\* Nonlinearity  $\pm 0.4$  °C

**Response time in fluid**
*Temperature sensor response time*

 Response time in fluid ( $T_{90}$ ) = 360 s

**Appendix**
**MTTFd Values**

MTTFd values are calculated per ISO 13849, assuming 50 % of all failures are dangerous.

Duty cycle is 67% and main operating temperature assumption is 80 °C. According to the internal Danfoss standard 504H0078, the daily working time is calculated with 8 hours/day and 200 working days per year.

Sensor	Order Number	
	149055	11232698
Supply voltage	4,5-8V	7-32V
Speed Signals	two	two
MTTFd values	2098 years	301 years





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